



## COMMON FIXED POINT THEOREMS ON $(\varphi, \psi)$ -TYPE MULTI VALUED MAPPINGS IN $b$ -METRIC SPACES

R. JAHIR HUSSAIN, K. MAHESHWARAN and D. DHAMODHARAN

<sup>1,2,3</sup>Jamal Mohamed College (Autonomous)  
(Affiliated to Bharathidasan University)  
Tiruchirappalli-620020, Tamilnadu India  
E-mail: hssn\_jhr@yahoo.com  
mahesksamy@gmail.com  
dharan\_raj28@yahoo.co.in

### Abstract

In this paper, we prove a fixed point theorem and a common fixed point theorem for new type of generalized multi-valued contractive mappings, via the class functions  $\Phi$  and  $\Psi$ . The main theorem is an extension of the common fixed point theorem for  $(\varphi, \psi)$ -type multi-valued mappings on complete  $b$ -metric spaces. The conditions for existence and uniqueness of the common fixed point are investigated.

### Introduction

In 1922, Stefan Banach [3] proved a fixed point theorem for contractive mappings in complete metric spaces. In 1969, Nadler [13] introduced the concept of Multivalued function. Later, Czerwik [5, 6] initiated the concept of  $b$ -metrics which generalized usual metric spaces. After his contribution, many results were presented in  $\beta$ -generalized weak contractive multifunctions and  $b$ -metric spaces. In 2012, Aydi et al. [2] reformulated the  $b$ -metric space. Many researchers work in this area of research of multivalued function and  $b$ -metric spaces [1, 4, 7, 8, 9-12, 14]. The following definitions will be needed in the sequel:

**Definition 1** [13]. Let  $X$  and  $Y$  be nonempty sets.  $T$  is said to be multi-valued mapping from  $X$  to  $Y$  if  $T$  is a function from  $X$  to the power set of  $Y$ . We

---

2020 Mathematics Subject Classification: Primary 54H25; Secondary 54H20.

Keywords:  $b$ -Metric space, multi-valued mappings, fixed point, common fixed point.

Received September 13, 2021; Accepted November 2021

denote a multi-valued map by  $T : X \rightarrow 2^Y$ .

**Definition 2** [13]. A point of  $x_0 \in X$  is said to be a fixed point of the multi-valued mapping  $T$  if  $x_0 \in Tx_0$ .

**Definition 3** [13]. Let  $(X, D_b)$  be a metric space. A map  $T : X \rightarrow X$  is called contraction if there exists  $0 \leq s < 1$  such that  $d(Tx, Ty) \leq s d(x, y)$ , for all  $x, y \in X$ .

**Definition 4** [13]. Let  $(X, D_b)$  be a metric space. We define the Hausdorff metric on  $CB(X)$  induced by  $D_b$ . That is  $H(A, B) = \max \{ \sup_{x \in A} D_b(x, B), \sup_{y \in B} D_b(y, A) \}$  for all  $A, B \in CB(X)$ , where  $CB(X)$  denotes the family of all non-empty closed and bounded subsets of  $X$  and  $D_b(x, B) = \inf \{ D_b(x, b) : b \in B \}$ , for all  $x \in X$ .

**Definition 5** [13]. Let  $(X, D_b)$  be a metric space. A map  $T : X \rightarrow CB(X)$  is  $\alpha_i$  to be multi-valued contraction if there exists  $0 \leq s < 1$  such that  $H(Tx, Ty) \leq s D_b(x, y)$ , for all  $x, y \in X$ .

**Lemma 6** [13]. If  $A, B \in CB(X)$  and  $a \in A$ , then for each  $\epsilon > 0$ , there exists  $b \in B$  such that  $D_b(a, b) \leq H(A, B) + \epsilon$ .

**Definition 7** [2]. Let  $X$  be a non-empty set and let  $s \geq 1$  be a given real number. A function  $D_b : X \times X \rightarrow R^+$  is called a  $b$ -metric provide that, for all  $x, y, z \in X$ ,

$$(d1) \quad D_b(x, y) = 0 \text{ if and only if } x = y,$$

$$(d2) \quad D_b(x, y) = D_b(y, x);$$

$$(d3) \quad D_b(x, z) \leq s[D_b(x, y) + D_b(y, z)].$$

A pair  $(X, D_b)$  is called a  $b$ -metric space.

**Example 8** [9]. The space  $l^p = \{ (x_n : \sum_{n=1}^{\infty} |x_n|^p < \infty, 0 < p < 1) \}$ , together with the function  $D_b : l^p \times l^p \rightarrow R^+$ .

**Definition 9** [2]. Let  $(X, D_b)$  be a  $b$ -metric space. Then a sequence  $(x_n)$  in  $X$  is called Cauchy sequence if and only if for all  $\epsilon > 0$  there exists  $n(\epsilon) \in \mathbb{R}$  such that for each  $m, n \geq n(\epsilon)$  we have  $D_b(x_n, x_m) < \epsilon$ .

**Definition 10** [2]. Let  $(X, D_b)$  be a  $b$ -metric space. Then a sequence  $(x_n)$  in  $X$  is called convergent sequence if and only if there exists  $x \in X$  such that for all  $\epsilon > 0$  there exists  $n(\epsilon) \in \mathbb{R}$  such that for all  $n \geq n(\epsilon)$  we have  $D_b(x_n, x) < \epsilon$ . In this case we write  $\lim_{n \rightarrow \infty} x_n = x$ .

**Definition 11** [7]. Let  $\psi$  be the family of all functions  $\psi : \mathbb{R}_0^+ \rightarrow \mathbb{R}_0^+$  such that

- (1)  $\psi$  is non-decreasing
- (2)  $\lim_{n \rightarrow \infty} \psi_n(t) = 0$  for all  $t \geq 0$ , where  $\psi^n$  stands for the  $n^{\text{th}}$  iterate of  $\psi$ .

**Example 12** [7]. Let

1.  $\psi_1(t) = \alpha t$ ,  $0 < \alpha < 1$ , for all  $t \geq 0$ ,
2.  $\psi_2(t) = \frac{t}{1+t}$ , for all  $t \geq 0$ ,

**Definition 13** [7]. Let  $\Phi$  be the family of all functions  $\varphi : \mathbb{R}_0^+ \rightarrow \mathbb{R}_0^+$  such that:

- (1)  $\varphi$  is non-decreasing and continuous;
- (2) For each sequence  $\{t_n\} \subset (0, \infty)$ ,  $\lim_{n \rightarrow \infty} \varphi(t_n) = 0$  if and only if  $\lim_{n \rightarrow \infty} t_n = 0$ .
- (3)  $\varphi(kt) = k\varphi(t)$ , for some  $k > 0$ .

**Example 14** [7]. Let

1.  $\varphi_1(t) = t$
2.  $\varphi_2(t) = ef(t)$ ,  $f \in F$ ,  $\forall t > 0$ .

### Main Results

We prove a unique fixed point for generalised multi-valued  $(\varphi, \psi)$ -contraction mapping via the class functions  $\Phi$  and  $\Psi$ .

**Theorem 15.** *Let  $(X, D_b)$  be a complete  $b$ -metric space with constant  $s \geq 1$ . Let  $f : X \rightarrow CB(X)$  be define a generalised multi-valued  $(\psi, \varphi)$ -contraction mapping if there exist  $\psi \in \Psi$  and  $\varphi \in \Phi$  such that for all  $x, y \in X$ ,*

$$\varphi(H(fx, fy)) \leq \psi(\varphi(M(x, y))) \quad (1.1)$$

where,

$$\begin{aligned} M(x, y) = & \alpha_1 D_b(x, fx) + \alpha_2 D_b(y, fy) + \alpha_3 D_b(x, fy) + \alpha_4 D_b(y, fx) \\ & + \alpha_5 D_b(x, y) + \alpha_6 \frac{D_b(x, fx)(1 + D_b(x, fx))}{1 + D_b(x, y)} \end{aligned}$$

for all  $x, y \in X$  and  $\alpha_i \geq 0, i = 1, 2, 3, \dots, 6$  with  $\alpha_1 + \alpha_2 + 2s\alpha_3 + \alpha_4 + \alpha_5 + \alpha_6 < 1$ . Then  $f$  has a unique fixed point.

**Proof.** Fix any  $x \in X$ . Define  $x_0 = x$  and let  $x_1 \in fx_0$ . By Lemma 6, we may choose  $x_2 \in fx_1$  such that

$$\varphi(D_b(x_1, x_2)) \leq \varphi(H(fx_0, fx_1) + (\alpha_1 + s\alpha_3 + \alpha_5 + \alpha_6)).$$

Now,

$$\begin{aligned} \varphi(D_b(x_1, x_2)) & \leq \varphi(H(fx_0, fx_1)) \\ & \leq \psi \left( \varphi \left( \left( \alpha_1 D_b(x_0, fx_0) + \alpha_2 D_b(x_1, fx_1) + \alpha_3 D_b(x_0, fx_1) + \alpha_4 D_b(x_1, fx_0) \right) \right. \right. \\ & \quad \left. \left. + \alpha_5 D_b(x_0, x_1) + \alpha_6 \left( \frac{D_b(x_0, fx_0)(1 + D_b(x_0, fx_0))}{1 + D_b(x_0, x_1)} \right) \right) \right) \\ & = \psi \left( \varphi \left( \left( \alpha_1 D_b(x_0, x_1) + \alpha_2 D_b(x_1, x_2) + \alpha_3 D_b(x_0, x_2) + \alpha_4 D_b(x_1, x_1) \right) \right. \right. \\ & \quad \left. \left. + \alpha_5 D_b(x_0, x_1) + \alpha_6 \left( \frac{D_b(x_0, x_1)(1 + D_b(x_0, x_1))}{1 + D_b(x_0, x_1)} \right) \right) \right) \\ & \leq \psi \left( \varphi \left( \left( \alpha_1 D_b(x_0, x_1) + \alpha_2 D_b(x_1, x_2) + \alpha_3 D_b(x_0, x_2) + \alpha_4 D_b(x_1, x_1) \right) \right. \right. \\ & \quad \left. \left. + \alpha_5 D_b(x_0, x_1) + \alpha_6 (D_b(x_0, x_1)) \right) \right) \end{aligned}$$

$$\begin{aligned}
&\leq \psi \left( \varphi \left( \begin{aligned} &((\alpha_1 + \alpha_5 + \alpha_6)D_b(x_0, x_1) + \alpha_2 D_b(x_1, x_2)) \\ &+ \alpha_3 s[D_b(x_0, x_1) + D_b(x_1, x_2)] \end{aligned} \right) \right) \\
&\leq \psi \left( \varphi \left( \begin{aligned} &((\alpha_1 + s\alpha_3 + \alpha_5 + \alpha_6)D_b(x_0, x_1)) \\ &+ \alpha_2 D_b(x_1, x_2) + s\alpha_3 D_b(x_1, x_2) \end{aligned} \right) \right) \\
&\leq \psi \left( \varphi \left( \begin{aligned} &((\alpha_1 + s\alpha_3 + \alpha_5 + \alpha_6)D_b(x_0, x_1)) \\ &+ (\alpha_2, s\alpha_3) + D_b(x_1, x_2) \end{aligned} \right) \right) \\
&\leq \psi \left( \varphi \left( \begin{aligned} &((\alpha_1 + s\alpha_3 + \alpha_5 + \alpha_6)D_b(x_0, x_1)) \\ &+ (\alpha_2, s\alpha_3)\varphi D_b(x_1, x_2) \end{aligned} \right) \right) \\
&\leq \psi \left( \frac{\alpha_1 + s\alpha_3 + \alpha_5 + \alpha_6}{1 + (\alpha_2, s\alpha_3)} \varphi(D_b(x_0, x_1)) \right).
\end{aligned}$$

There exist  $x_3 \in fx_2$  such that

$$\varphi(D_b(x_2, x_3)) \leq \varphi \left( H(fx_1, fx_2) + \frac{\alpha_1 + s\alpha_3 + \alpha_5 + \alpha_6}{1 + (\alpha_2, s\alpha_3)} \right)$$

Now,

$$\begin{aligned}
\varphi(D_b(x_2, x_3)) &\leq \varphi \left( H(fx_1, fx_2) + \frac{\alpha_1 + s\alpha_3 + \alpha_5 + \alpha_6}{1 + (\alpha_2, s\alpha_3)} \right) \\
&\leq \varphi(H(fx_1, fx_2)) \\
&\leq \psi \left( \varphi \left( \begin{aligned} &(\alpha_1 D_b(x_1, fx_1) + \alpha_2 D_b(x_2, fx_2) + \alpha_3 D_b(x_1, fx_2) + \alpha_4 D_b(x_2, fx_1)) \\ &+ \alpha_5 D_b(x_1, x_2) + \alpha_6 \left( \frac{D_b(x_1, fx_1)(1 + D_b(x_1, fx_1))}{1 + D_b(x_1, x_2)} \right) \end{aligned} \right) \right) \\
&= \psi \left( \varphi \left( \begin{aligned} &(\alpha_1 D_b(x_1, x_2) + \alpha_2 D_b(x_2, x_3) + \alpha_3 D_b(x_1, x_3) + \alpha_4 D_b(x_2, x_2)) \\ &+ \alpha_5 D_b(x_1, x_2) + \alpha_6 \left( \frac{D_b(x_1, x_2)(1 + D_b(x_1, x_2))}{1 + D_b(x_1, x_2)} \right) \end{aligned} \right) \right) \\
&\leq \psi \left( \varphi \left( \begin{aligned} &(\alpha_1 D_b(x_1, x_2) + \alpha_2 D_b(x_2, x_3) + \alpha_3 D_b(x_1, x_3) + \alpha_4 D_b(x_2, x_2)) \\ &+ \alpha_5 D_b(x_1, x_2) + \alpha_6 (D_b(x_1, x_2)) \end{aligned} \right) \right) \\
&\leq \psi \left( \varphi \left( \begin{aligned} &((\alpha_1 + \alpha_5 + \alpha_6)D_b(x_1, x_2) + \alpha_2 D_b(x_2, x_3)) \\ &+ \alpha_3 s[D_b(x_1, x_2) + D_b(x_2, x_3)] \end{aligned} \right) \right)
\end{aligned}$$

$$\begin{aligned}
&\leq \psi\left(\varphi\left(\begin{array}{l} (\alpha_1 + s\alpha_3 + \alpha_5 + \alpha_6)D_b(x_1, x_2) \\ + \alpha_2 D_b(x_2, x_3) + s\alpha_3 D_b(x_2, x_3) \end{array}\right)\right) \\
&\leq \psi\left(\varphi\left(\begin{array}{l} (\alpha_1 + s\alpha_3 + \alpha_5 + \alpha_6)D_b(x_1, x_2) \\ + (\alpha_2, s\alpha_3) + D_b(x_2, x_3) \end{array}\right)\right) \\
&\leq \psi\left(\begin{array}{l} (\alpha_1 + s\alpha_3 + \alpha_5 + \alpha_6)D_b(x_1, x_2) \\ + (\alpha_2, s\alpha_3)\varphi D_b(x_2, x_3) \end{array}\right) \\
&\leq \psi\left(\frac{\alpha_1 + s\alpha_3 + \alpha_5 + \alpha_6}{1 + (\alpha_2, s\alpha_3)} \varphi(D_b(x_1, x_2))\right).
\end{aligned}$$

Continuing this process, we obtain by induction a sequence  $\{x_n\}$  such that  $x_n \in fx_{n-1}$ ,  $x_{n-1} \in fx_n$  such that

$$\begin{aligned}
\varphi(D_b(x_n, x_{n-1})) &\leq \varphi\left(H(fx_{n-1}, fx_n) + \frac{\alpha_1 + s\alpha_3 + \alpha_5 + \alpha_6}{1 + (\alpha_2, s\alpha_3)}\right) \\
&\leq \varphi(H(fx_{n-1}, fx_n)) \\
&\leq \psi\left(\varphi\left(\begin{array}{l} \alpha_1 D_b(x_{n-1}, fx_{n-1}) + \alpha_2 D_b(x_n, fx_n) + \alpha_3 D_b(x_{n-1}, fx_n) + \alpha_4 D_b(x_n, fx_{n-1}) \\ + \alpha_5 D_b(x_{n-1}, x_n) + \alpha_6 \left(\frac{D_b(x_{n-1}, fx_{n-1})(1 + D_b(x_{n-1}, fx_{n-1}))}{1 + D_b(x_{n-1}, x_n)}\right) \end{array}\right)\right) \\
&= \psi\left(\varphi\left(\begin{array}{l} \alpha_1 D_b(x_{n-1}, x_n) + \alpha_2 D_b(x_n, x_{n+1}) + \alpha_3 D_b(x_{n-1}, x_{n+1}) + \alpha_4 D_b(x_n, x_n) \\ + \alpha_5 D_b(x_{n-1}, x_n) + \alpha_6 \left(\frac{D_b(x_{n-1}, x_n)(1 + D_b(x_{n-1}, x_n))}{1 + D_b(x_{n-1}, x_n)}\right) \end{array}\right)\right) \\
&\leq \psi\left(\varphi\left(\begin{array}{l} \alpha_1 D_b(x_{n-1}, x_n) + \alpha_2 D_b(x_n, x_{n+1}) + \alpha_3 D_b(x_{n-1}, x_{n+1}) + \alpha_4 D_b(x_n, x_n) \\ + \alpha_5 D_b(x_{n-1}, x_n) + \alpha_6 (D_b(x_{n-1}, x_n)) \end{array}\right)\right) \\
&\leq \psi\left(\varphi\left(\begin{array}{l} (\alpha_1 + \alpha_5 + \alpha_6)D_b(x_{n-1}, x_n) + \alpha_2 D_b(x_n, x_{n+1}) \\ + \alpha_3 s[D_b(x_{n-1}, x_n) + D_b(x_n, x_{n+1})] \end{array}\right)\right) \\
&\leq \psi\left(\varphi\left(\begin{array}{l} (\alpha_1 + s\alpha_3 + \alpha_5 + \alpha_6)D_b(x_{n-1}, x_n) \\ + \alpha_2 D_b(x_n, x_{n+1}) + s\alpha_3 D_b(x_n, x_{n+1}) \end{array}\right)\right) \\
&\leq \psi\left(\varphi\left(\begin{array}{l} (\alpha_1 + s\alpha_3 + \alpha_5 + \alpha_6)D_b(x_{n-1}, x_n) \\ + (\alpha_2, s\alpha_3) + D_b(x_n, x_{n+1}) \end{array}\right)\right)
\end{aligned}$$

$$\begin{aligned} &\leq \psi \left( \begin{array}{l} (\alpha_1 + s\alpha_3 + \alpha_5 + \alpha_6)D_b(x_{n-1}, x_n) \\ + (\alpha_2, s\alpha_3)\varphi D_b(x_n, x_{n+1}) \end{array} \right) \\ &\leq \psi \left( \frac{(\alpha_1 + s\alpha_3 + \alpha_5 + \alpha_6)}{1 + (\alpha_2, s\alpha_3)} \varphi(D_b(x_{n-1}, x_n)) \right) \end{aligned}$$

for all  $n \in N$  and let

$$\begin{aligned} \delta &= \left[ \frac{\alpha_1 + s\alpha_3 + \alpha_5 + \alpha_6}{1 + (\alpha_2, s\alpha_3)} \right] \\ \varphi(D_b(x_n, x_{n+1})) &\leq \delta(\psi(\varphi(D_b(x_{n-1}, x_n)))) \\ &\leq \delta[\delta(\psi(\varphi(D_b(x_{n-2}, x_{n-1}))))] \\ &= \delta^2(\psi(\varphi(D_b(x_{n-2}, x_{n-1})))) \\ &\quad \vdots \\ &\leq \delta^n(\psi(\varphi(D_b(x_0, x_1)))). \end{aligned}$$

Since  $\delta < 1$ ,  $\Sigma \delta^n$  have a radius of convergence. Then,  $\{x_n\}$  is a Cauchy sequence. But  $(X, D_b)$  is a complete b-metric space, it follows that  $\{x_n\}_{n=1}^\infty$  is convergent  $u = \lim_{n \rightarrow \infty} x_n$ .

Now,

$$\begin{aligned} \varphi(D_b(q, fq)) &\leq \psi(\varphi[s[D_b(q, x_{n+1}) + D_b(x_{n+1}, fq)]]) \\ &\leq \varphi[s[D_b(q, x_{n+1}) + D_b(x_n, fq)]] \end{aligned}$$

Using (1.1), we obtain,

$$\varphi(D_b(q, fq)) \leq \psi \left( \varphi \left( \begin{array}{l} s[D_b(q, x_{n+1})] \\ + \left( s \left[ \begin{array}{l} \alpha_1 D_b(x_n, fx_n) + \alpha_2 D_b(q, fq) + \alpha_3 D_b(x_n, fq) \\ + \alpha_4 D_b(q, fx_n) + \alpha_5 D_b(x_n, q) + \alpha_6 D_b(x_n, q) \end{array} \right] \right) \end{array} \right) \right)$$

As  $n \rightarrow \infty$ ,  $\varphi(D_b(q, fq)) \leq \psi(\varphi[s[\alpha_2 D_b(q, fq) + \alpha_3 D_b(q, fq)])$

$$(1 - (\alpha_2 s + \alpha_3 s))D_b(q, fq) \leq 0.$$

Which is not true,  $\varphi(D_b(q, fq)) = 0$ . Thus,  $fq = q$ .

Now, show that  $q$  is the unique fixed point of  $f$ . Assume that  $r$  is another fixed point of  $f$ . Then we have  $fr = r$  and

$$\begin{aligned}\varphi(D_b(q, r)) &= \varphi(D_b(fq, fr)) \\ &\leq \varphi(s[D_b(q, fr) + D_b(r, fq)])\end{aligned}$$

Which implies that,  $\varphi(D_b(q, r)) \leq 2sD_b(q, r)$ . This implies  $q = r$ .

**Corollary 16.** *Let  $(X, D_b)$  be a complete  $b$ -metric space with constant  $s \geq 1$ . Let  $f : X \rightarrow CB(X)$  be define a generalised multi-valued  $(\psi, \varphi)$ -contraction mapping if there exist  $\psi \in \Psi$  and  $\varphi \in \Phi$  such that for all  $x, y \in X$ ,*

$$\varphi(H(fx, fy)) \leq \psi\left(\varphi\left(\alpha D_b(x, fx) + \beta \frac{D_b(x, fy)(1 + D_b(x, fx))}{1 + D_b(x, y)}\right)\right)$$

for all  $x, y \in X$  and  $\alpha, \beta \geq 0$ , with  $\alpha + s\beta < 1$ . Then  $f$  has a unique fixed point.

Next, we need to prove a unique common fixed point for generalised multi-valued  $(\psi, \varphi)$ -contraction mappings via the class functions  $\Phi$  and  $\Psi$ .

**Theorem 17.** *Let  $(X, D_b)$  be a complete  $b$ -metric space with constant  $s \geq 1$ . Let  $f, g : X \rightarrow CB(X)$  be generalized multi-valued  $(\psi, \varphi)$ -contraction mapping, satisfies the condition:*

$$\begin{aligned}\varphi(H(fx, gy)) &\leq \psi(\varphi(\alpha_1 D_b(x, fx) + \alpha_2 D_b(y, gy) \\ &\quad + \alpha_3 D_b(x, gy) + \alpha_4 D_b(y, fx) + \alpha_5 D_b(x, y))),\end{aligned}$$

Where, there exists  $\psi \in \Psi, \varphi \in \Phi$  such that for all  $x, y \in X$  and  $\alpha_i \geq 0, i = 1, 2, \dots, 5$ , with  $(\alpha_1 + \alpha_2)(s + 1) + (\alpha_3 + \alpha_4)(s_2 + s) + 2s\alpha_5 < 2$ ,  $\alpha_1 + \alpha_2 + \alpha_3 + \alpha_4 + \alpha_5 < 1$ . Then  $f$  and  $g$  have a unique common fixed point.

**Proof.** Fix any  $x \in X$ . Define  $x_0 = x$  and let  $x_1 \in fx_0, x_2 \in gx_1$  such that  $x_{2n+1} = fx_{2n}, x_{2n+2} = gx_{2n+1}$ , choose  $x_2 \in gx_1$  such that

$$\varphi(D_b(x_1, x_2)) \leq \varphi(H(fx_0, gx_1) + (\alpha_1 + \alpha_5 + s\alpha_3))$$



$$\begin{aligned}
&\leq \varphi(H(fx_0, gx_1)) \\
\varphi(D_b(x_1, x_2)) &\leq \psi\left(\varphi\left(\begin{array}{c} \alpha_1 D_b(x_0, fx_0) + \alpha_2 D_b(x_1, gx_1) + \alpha_3 D_b(x_0, gx_1) \\ + \alpha_4 D_b(x_1, fx_0) + \alpha_5 D_b(x_0, x_1) \end{array}\right)\right) \\
&= \psi\left(\varphi\left(\begin{array}{c} \alpha_1 D_b(x_0, x_1) + \alpha_2 D_b(x_1, x_2) + \alpha_3 D_b(x_0, x_2) \\ + \alpha_4 D_b(x_2, x_2) + \alpha_5 D_b(x_0, x_1) \end{array}\right)\right) \\
&\leq \psi\left(\varphi\left(\begin{array}{c} \alpha_1 D_b(x_0, x_1) + \alpha_2 D_b(x_1, x_2) \\ + \alpha_3 s[D_b(x_0, x_1) + D_b(x_1, x_2)] + \alpha_5 D_b(x_0, x_1) \end{array}\right)\right) \\
&\leq \psi(\varphi((\alpha_1 + s\alpha_3 + \alpha_5)D_b(x_0, x_1) + (\alpha_2 + s\alpha_3)D_b(x_1, x_2))) \\
&\leq \psi\left(\frac{\alpha_1 + \alpha_5 + s\alpha_3}{1 - (\alpha_2 + s\alpha_3)} \varphi(D_b(x_0, x_1))\right) \tag{1.2}
\end{aligned}$$

Then,

$$\begin{aligned}
\varphi(D_b(x_2, x_1)) &= \varphi(D_b(gx_1, fx_0)) \\
&\leq \varphi(H(gx_1, fx_0) + (\alpha_2 + \alpha_5 + s\alpha_4)) \\
&\leq \varphi(H(gx_1, fx_0)) \\
&\leq \psi\left(\varphi\left(\begin{array}{c} \alpha_1 D_b(x_1, gx_1) + \alpha_2 D_b(x_0, fx_0) + \alpha_3 D_b(x_1, fx_0) \\ + \alpha_4 D_b(x_0, gx_1) + \alpha_5 D_b(x_1, x_0) \end{array}\right)\right) \\
&= \psi\left(\varphi\left(\begin{array}{c} \alpha_1 D_b(x_1, x_2) + \alpha_2 D_b(x_0, x_1) + \alpha_3 D_b(x_1, x_1) \\ + \alpha_4 D_b(x_0, x_2) + \alpha_5 D_b(x_0, x_1) \end{array}\right)\right) \\
&\leq \psi\left(\varphi\left(\begin{array}{c} \alpha_1 D_b(x_1, x_2) + \alpha_2 D_b(x_0, x_1) \\ + \alpha_4 s[D_b(x_0, x_1) + D_b(x_1, x_2)] + \alpha_5 D_b(x_0, x_1) \end{array}\right)\right) \\
&= \psi(\varphi((\alpha_2 + \alpha_5 + s\alpha_4)D_b(x_0, x_1) + (\alpha_1 + s\alpha_4)D_b(x_2, x_1))) \\
&\leq \psi\left(\frac{\alpha_2 + \alpha_5 + s\alpha_4}{1 - (\alpha_1 + s\alpha_4)} \varphi(D_b(x_0, x_1))\right) \tag{1.3}
\end{aligned}$$

Adding inequalities (1.2) and (1.3), we obtain  $D_b(x_1, x_2)$  where,

$$\varphi(D_b(x_1, x_2)) \leq \left(\frac{(\alpha_1 + \alpha_2 + s\alpha_3 + s\alpha_4 + 2\alpha_5)}{2 - (\alpha_1 + \alpha_2 + s\alpha_3 + s\alpha_4)} \varphi(D_b(x_0, x_1))\right)$$

where,

$$\delta = \frac{(\alpha_1 + \alpha_2 + s\alpha_3 + s\alpha_4 + 2\alpha_5)}{2 - (\alpha_1 + \alpha_2 + s\alpha_3 + s\alpha_4)} < \frac{1}{s}.$$

Similarly, it can be shown that, there exists  $x_3 \in fx_2$  such that

$$\varphi(D_b(x_3, x_2)) \leq \varphi(H(fx_2, gx_1)) \leq \psi(\delta\varphi(D_b(x_1, x_0)))$$

Continuing this process, we obtain by induction a sequence  $\{x_n\}$  such that  $x_{2n+1} \in fx_{2n}$ ,  $x_{2n+2} \in gx_{2n+1}$  such that

$$\begin{aligned} \varphi(D_b(x_{2n+1}, x_{2n+2})) &\leq \varphi(H(fx_{2n}, gx_{2n+1})) \\ &\leq \psi\left(\varphi\left(\alpha_1 D_b(x_{2n}, fx_{2n}) + \alpha_2 D_b(x_{2n+1}, gx_{2n+1}) + \alpha_3 D_b(x_{2n}, gx_{2n+1})\right.\right. \\ &\quad \left.\left.+ \alpha_4 D_b(x_{2n+1}, fx_{2n}) + \alpha_5 D_b(x_{2n}, x_{2n+1})\right)\right) \\ &= \psi\left(\varphi\left(\alpha_1 D_b(x_{2n}, x_{2n+1}) + \alpha_2 D_b(x_{2n+1}, x_{2n+2}) + \alpha_3 D_b(x_{2n}, x_{2n+2})\right.\right. \\ &\quad \left.\left.+ \alpha_4 D_b(x_{2n+1}, x_{2n+1}) + \alpha_5 D_b(x_{2n}, x_{2n+1})\right)\right) \\ &\leq \psi\left(\varphi\left(\alpha_1 D_b(x_{2n}, x_{2n+1}) + \alpha_2 D_b(x_{2n+1}, x_{2n+2})\right.\right. \\ &\quad \left.\left.+ \alpha_3 s[D_b(x_{2n}, x_{2n+1}) + D_b(x_{2n+1}, x_{2n+2})] + \alpha_5 D_b(x_{2n}, x_{2n+1})\right)\right) \\ &= \psi\left(\varphi\left(\alpha_1 + \alpha_5 + s\alpha_3\right) D_b(x_{2n}, x_{2n+1})\right) \\ &\quad \left.\left.+ \varphi\left(\alpha_2 + s\alpha_3\right) D_b(x_{2n+1}, x_{2n+2})\right)\right) \\ &\leq \psi\left(\frac{\alpha_1 + \alpha_5 + s\alpha_3}{1 - (\alpha_2 + s\alpha_3)} \varphi(D_b(x_{2n}, x_{2n+1}))\right) \end{aligned} \tag{1.4}$$

also,

$$\begin{aligned} \varphi(D_b(x_{2n+2}, x_{2n+1})) &\leq \varphi(H(gx_{2n+1}, fx_{2n})) \\ &\leq \psi\left(\varphi\left(\alpha_1 D_b(x_{2n+1}, gx_{2n+1}) + \alpha_2 D_b(x_{2n}, fx_{2n}) + \alpha_3 D_b(x_{2n+1}, fx_{2n})\right.\right. \\ &\quad \left.\left.+ \alpha_4 D_b(x_{2n}, gx_{2n+1}) + \alpha_5 D_b(x_{2n+1}, x_{2n})\right)\right) \\ &= \psi\left(\varphi\left(\alpha_1 D_b(x_{2n+1}, x_{2n+2}) + \alpha_2 D_b(x_{2n}, x_{2n+1}) + \alpha_3 D_b(x_{2n+1}, x_{2n+1})\right.\right. \\ &\quad \left.\left.+ \alpha_4 D_b(x_{2n}, x_{2n+2}) + \alpha_5 D_b(x_{2n+1}, x_{2n})\right)\right) \\ &\leq \psi\left(\varphi\left(\alpha_1 D_b(x_{2n+1}, x_{2n+2}) + \alpha_2 D_b(x_{2n}, x_{2n+1})\right.\right. \\ &\quad \left.\left.+ \alpha_3 s[D_b(x_{2n}, x_{2n+1}) + D_b(x_{2n+1}, x_{2n+2})] + \alpha_5 D_b(x_{2n+1}, x_{2n})\right)\right) \end{aligned}$$

$$\begin{aligned}
&= \psi \left( \varphi \left( \begin{array}{l} (\alpha_2 + \alpha_5 + s\alpha_4)D_b(x_{2n}, x_{2n+1}) \\ + (\alpha_1 + s\alpha_4)D_b(x_{2n+1}, x_{2n+2}) \end{array} \right) \right) \\
&\leq \psi \left( \frac{\alpha_2 + \alpha_5 + s\alpha_4}{1 - (\alpha_1 + s\alpha_4)} \varphi(D_b(x_{2n}, x_{2n+1})) \right) \tag{1.5}
\end{aligned}$$

From (1.4) and (1.5)

$$\varphi(D_b(x_{2n+1}, x_{2n+2})) \leq \psi(\delta\varphi(D_b(x_{2n}, x_{2n+1}))).$$

Therefore,

$$\begin{aligned}
\varphi(D_b(x_n, x_{n+1})) &\leq \varphi(H(fx_{n-1}, gx_n)) \\
&\leq \psi \left( \varphi \left( \begin{array}{l} \alpha_1 D_b(x_{n-1}, fx_{n-1}) + \alpha_2 D_b(x_n, gx_n) + \alpha_3 D_b(x_{n-1}, gx_n) \\ + \alpha_4 D_b(x_n, fx_{n-1}) + \alpha_5 D_b(x_{n-1}, x_n) \end{array} \right) \right) \\
&= \psi \left( \varphi \left( \begin{array}{l} \alpha_1 D_b(x_{n-1}, x_n) + \alpha_2 D_b(x_n, x_{n+1}) + \alpha_3 D_b(x_{n-1}, x_{n+1}) \\ + \alpha_4 D_b(x_n, x_n) + \alpha_5 D_b(x_{n-1}, x_n) \end{array} \right) \right) \\
&\leq \psi \left( \varphi \left( \begin{array}{l} \alpha_1 D_b(x_{n-1}, x_n) + \alpha_2 D_b(x_n, x_{n+1}) \\ + \alpha_3 s [D_b(x_{n-1}, x_n) + D_b(x_n, x_{n+1})] + \alpha_5 D_b(x_{n-1}, x_n) \end{array} \right) \right) \\
&= \psi \left( \varphi \left( \begin{array}{l} (\alpha_1 + \alpha_5 + s\alpha_3)D_b(x_{n-1}, x_n) \\ + (\alpha_2 + s\alpha_3)D_b(x_n, x_{n+1}) \end{array} \right) \right) \\
&\leq \psi \left( \frac{\alpha_1 + \alpha_5 + s\alpha_3}{1 - (\alpha_2 + s\alpha_3)} \varphi(D_b(x_{n-1}, x_n)) \right) \tag{1.6}
\end{aligned}$$

Therefore,

$$\varphi(D_b(x_{n-1}, x_n)) \leq \left( \frac{(\alpha_1 + \alpha_2 + s\alpha_3 + s\alpha_4 + 2\alpha_5)}{2 - (\alpha_1 + \alpha_2 + s\alpha_3 + s\alpha_4)} \varphi(D_b(x_{n-1}, x_n)) \right)$$

$n \in N$  and let

$$\delta = \frac{(\alpha_1 + \alpha_2 + s\alpha_3 + s\alpha_4 + 2\alpha_5)}{2 - (\alpha_1 + \alpha_2 + s\alpha_3 + s\alpha_4)}$$

$$\begin{aligned}
\varphi(D_b(x_n, x_{n+1})) &\leq \delta(\psi(\varphi(D_b(x_{n-1}, x_n)))) \\
&\leq \delta[\delta(\psi(\varphi(D_b(x_{n-2}, x_{n-1}))))]
\end{aligned}$$

$$\begin{aligned}
&= \delta^2(\psi(\varphi(D_b(x_{n-2}, x_{n-1})))) \\
&\quad \vdots \\
&\leq \delta^n(\psi(\varphi(D_b(x_0, x_1)))).
\end{aligned}$$

Since  $0 < \delta < 1$ ,  $\Sigma\delta^n$  have a radius of convergence. Then,  $\{x_n\}$  is a Cauchy sequence. Since  $(x, D_b)$  is complete, there exists  $u \in X$  such that  $x_n \rightarrow u$ . We shall prove that  $u$  is a common fixed point of  $f$  and  $g$ .

$$\begin{aligned}
\varphi(D_b(u, fu)) &\leq \psi(\varphi(s[D_b(u, x_{2n+1}) + D_b(x_{2n+1}, fu)])) \\
&\leq \psi(\varphi(s[D_b(u, x_{2n+1}) + H(x_{2n+1}, fu)])) \\
\varphi(D_b(u, gu)) &\leq \psi(\varphi(s[D_b(u, x_{2n+1}) + D_b(x_{2n+1}, gu)])) \\
&\leq \psi(\varphi(s[D_b(u, x_{2n+1}) + H(x_{2n+1}, gu)])) \tag{1.7}
\end{aligned}$$

Where,

$$\varphi(H(x_{2n}, gu)) \leq \psi\left(\varphi\left(\begin{aligned} &\alpha_1 D_b(x_{2n}, fx_{2n}) + \alpha_2 D_b(u, gu) + \alpha_3 D_b(x_{2n}, gu) \\ &+ \alpha_4 D_b(u, fx_{2n}) + \alpha_5 D_b(x_{2n}, u) \end{aligned}\right)\right) \tag{1.8}$$

Using (1.8) in (1.7) and letting as  $n \rightarrow \infty$ , we obtain,

$$\begin{aligned}
\varphi(D_b(u, gu)) &\leq (\varphi(s D_b(u, u))) \\
&\leq \psi\left(\varphi\left(s\left[\begin{aligned} &\alpha_1 D_b(u, u) + \alpha_2 D_b(u, gu) + \alpha_3 D_b(u, gu) \\ &+ \alpha_4 D_b(u, u) + \alpha_5 D_b(u, u) \end{aligned}\right]\right)\right) \\
&= \psi(\varphi(s[\alpha_2 D_b(u, gu) + \alpha_3 D_b(u, gu)])) \\
&\leq \psi(\varphi(s(\alpha_2 + \alpha_3)D_b(u, gu))) \\
&[1 - s(\alpha_2 + \alpha_3)]D_b(u, gu) \leq 0
\end{aligned}$$

Implies that,  $1 - s(\alpha_2 + \alpha_3) \leq 0$  and  $g(u)$  is closed. Thus,  $g(u) = u$ .

Similarly,  $f(u) = u$ . Now, show that  $u$  is the unique fixed point of  $g$  and  $f$ .

Now,

$$\varphi(D_b(u, v)) \leq \varphi(H(fu, gv))$$

$$\begin{aligned} &\leq \psi \left( \varphi \left( \begin{aligned} &\alpha_1 D_b(u, fu) + \alpha_2 D_b(v, gv) + \alpha_3 D_b(u, gv) \\ &+ \alpha_4 D_b(v, fu) + \alpha_5 D_b(u, v) \end{aligned} \right) \right) \\ &\leq \psi(\varphi(\alpha_3 D_b(u, v) + \alpha_4 D_b(u, v) + \alpha_5(u, v))) \end{aligned}$$

This is not true for  $[1 - (\alpha_3 + \alpha_4 + \alpha_5)] \geq 0$ ,  $D_b(u, v) = 0$ . Hence,  $g$  and  $f$  have a unique common fixed point.

**Corollary 18.** *Let  $(X, D_b)$  be a complete  $b$ -metric space with constant  $s \geq 1$ . Let  $f, g : X \rightarrow CB(X)$  be generalized multi-valued  $(\psi, \varphi)$ -contraction mapping, satisfies the condition:*

$$\varphi(H(fx, gy)) \leq (\varphi(\alpha D_b(x, gy) + \beta D_b(y, fx) + \gamma D_b(x, y)))$$

Where, there exists  $\psi \in \Psi$ ,  $\varphi \in \Phi$  such that for all  $x, y \in X$  and  $\alpha, \beta, \gamma \geq 0$ , with  $(\alpha + \beta)(s^2 + s) + 2s\gamma < 2$ ,  $\alpha + \beta + \gamma < 1$ . Then  $f$  and  $g$  have a unique common fixed point.

**Example 19.** Let  $X = [0, 1]$ . Define a function  $D_b : X \times X \rightarrow R^+$  by  $D_b(x, y) = |x - y|$ . Clearly,  $(X, D_b)$  is a complete  $b$ -metric space. Define  $\phi : R_0^+ \rightarrow R_0^+$  by  $\phi(t) = t$  for all  $t > 0$ . Then  $\phi \in \Phi$ . Also define  $\psi : R_0^+ \rightarrow R_0^+$  by  $\psi(t) = ut$  for all  $t > 0$ . Then  $\psi$  is a continuous comparison function.

Define the mapping  $f : X \rightarrow CB(X)$  by  $fx = \left[0, \frac{x}{6}\right]$ , for all  $x, y \in X$ .

Then,

$$\varphi(H(fx, fy)) \leq \psi(\varphi(M(x, y)))$$

where,

$$\begin{aligned} M(x, y) &= \alpha_1 D_b(x, fx) + \alpha_2 D_b(y, fy) + \alpha_3 D_b + \alpha_3 D_b(x, fy) + \alpha_4 D_b(y, fx) \\ &+ \alpha_5 D_b(x, y) + \alpha_6 \frac{D_b(x, fx)(1 + D_b(x, fx))}{1 + D_b(x, y)} \end{aligned}$$

$$\begin{aligned}
\varphi(H(fx, fy)) &\leq \psi \left( \varphi \left( \left( \alpha_1 \left| x - \frac{x}{6} \right| + \alpha_2 \left| y - \frac{y}{6} \right| + \alpha_3 \left| x - \frac{y}{6} \right| + \alpha_4 \left| y - \frac{x}{6} \right| \right) \right. \right. \\
&\quad \left. \left. + \alpha_5 |x - y| + \alpha_6 \left( \frac{\left| x - \frac{x}{6} \right| \left( 1 + \left| x - \frac{x}{6} \right| \right)}{1 + |x - y|} \right) \right) \right) \\
&\leq \psi \left( \phi \left( \frac{1}{6} |x - y| \right) \right), \text{ where } \left[ \alpha_1 = \alpha_2 = \alpha_3 = \alpha_4 = \alpha_6 = 0, \alpha_5 = \frac{1}{6} \right] \\
&\leq \psi \left( \frac{1}{6} |x - y| \right) \\
&\leq \frac{\mu}{6} |x - y|, \text{ for } 0 < \mu < 1 \\
&\leq \frac{\mu}{6} M(x, y) = \frac{\mu}{6} \phi(M(x, y)) \\
&\leq \psi(\varphi(M(x, y))).
\end{aligned}$$

Therefore,  $0 \in X$  is a unique fixed point of  $f$ .

### References

- [1] H. Alikhani, D. Gopal, M. A. Miandaragh, Sh. Rezapour and N. Shahzad, Some endpoint results for generalized weak contractive multifunction, *Sci. World J.* Article ID 948472, 7 (2013).
- [2] H. Aydi, Monica Felicia Bota, Erdal Karuinar and M. Slobodanka, A fixed point theorem for set-valued quasi-contractions in  $b$ -metric spaces, *Fixed Point Theory Appl.* 88 (2012), doi:10.1186/1687-1812-2012-88
- [3] S. Banach, Sur les operations dans les ensembles abstraits et leur application aux equations integrals, *Fundam Math* 3 (1922), 133-181.
- [4] M. Boriceanu, Fixed point theory for multivalued generalized contraction on a set with two  $b$ -metrics, *Stud Univ. Babeş-Bolyai. Math LIV* (3) (2009), 1-14.
- [5] S. Czerwik, Contraction mappings in  $b$ -metric spaces, *Acta Math Inform Univ. Ostraviensis* 1 (1993), 5-11.
- [6] S. Czerwik, Nonlinear set-valued contraction mappings in  $b$ -metric spaces, *Atti. Semin. Math. Fis. Univ. Modena* 46(2) (1998), 263-276.
- [7] D. Dhamodharan and R. Krishnakumar, Common fixed points of  $(\psi, \varphi)$ -weak contractions in regular cone metric spaces, *International Journal of Mathematical Archive* 8(8) (2017), 1-8.

- [8] R. Krishnakumar and D. Dhamodharan, Common fixed point of four mapping with contractive modulus on cone banach space, *Malaya J. Mat.* 5(2) (2017), 310-320.
- [9] D. Dhamodharan and R. Krishnakumar, Cone C-class function with common fixed point theorems for cone  $b$ -metric space, *Journal of Mathematics and Informatics* 8 (2017), 83-94.
- [10] H. Huang and S. Xu, Fixed point theorems of contractive mappings in cone  $b$ -metric spaces and applications, *Fixed point Theory Appl.* 112 (2013).
- [11] N. Hussain, M. H. Shah, KKM mapping in cone  $b$ -metric spaces, *Comput. Math. Appl.* 62(4) (2011), 1677-1684.
- [12] K. Mehemet and H. Kiziltunc, On some well-known fixed point theorems in  $b$ -metrics spaces, *Turk J. Anal Appl.* 1(1) (2013), 13-16.
- [13] B. SAM and JR. Nadler, Multi-valued contraction mappings, *Pac. J. Math.* 30 (1969), 475-488.
- [14] Z. Wang and H. Li, Fixed point theorems and endpoint theorems for  $(\alpha, \Psi)$ -Meir-Keeler-Khan Multivalued mapping, *Fixed Point Theory Appl.* 12 (2016).